# Energy Management in Low Power Wireless Sensor Networks









# **Energy Management in Low Power Wireless Sensor Networks Team 14**

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# **Preliminary Design**

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1 *Cover page image kindly provided by Visual Hunt [1]*

# **Revision History**



2 *Incrementing the version by 0.1 denotes a minor change; incrementing by 1.0 denotes a significant change*

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### <span id="page-5-0"></span>**1 Introduction**

The proliferation of data monitoring technologies has enabled multifarious insights into environmental conditions, system reliability, consumer behaviour, and a myriad of other fields and industries [2]. Sensors are one such technology, able to detect events or changes in their environment and send this information to other electronics. Energy storage poses a constraint on sensor operation in rural environments; a lack of grid connectivity exposes the importance of sagacious energy management.

#### **1.1 Overview**

Cloud Seven Consultants (CSC) has been contracted by ATAMO (the client) to investigate energy management in low-power wireless sensor networks (WSN). The project requires integration of a third party WSN with an ATAMO Arduino based development platform. Sensor data must be measured and periodically reported over the WSN to a cloud-based database. The firmware in the sensor must provide for reliable communications while keeping tight constraints on battery energy usage.

#### **1.2 Purpose**

The purpose of this document is to outline a high-level preliminary design of the WSN for ease of comprehension.

#### **1.3 Structure & Contributions**

CSC has identified three core sub-systems within the WSN – Hardware, Kernel and Front-End – as recommended by the client [3]. Individual sub-teams have been assigned to each core sub-system. The Hardware team is tasked with designing and fabricating the interposer printed circuit board (PCB) for the duinoPRO-Dusty module. The Kernel team is tasked with developing the firmware, communication packet structure for sensor motes and optimising battery usage. The Front-End team is tasked with data visualisation via the integration of cloud services.

This report is a high-level overview of the whole-system design. Detailed design decisions are outline in individual team volumes as listed in [Table 1.](#page-5-1) Report sections cover the design architecture, summarise individual volumes, requirements, resources, system cost and top three risks.

<span id="page-5-1"></span>





### **1.4 Definitions, Acronyms, and Abbreviations**





### <span id="page-7-0"></span>**2 Design Architecture**

This system implements a site-based wireless sensor network (WSN) which uses the Transmission Control Protocol/Internet Protocol (TCP/IP) to remotely transmit data to a client/developer for analysis whilst also being capable of remote configuration by the client/developer.



*Figure 1. Transactions between system end-points*

<span id="page-7-1"></span>[Figure 1](#page-7-1) shows the end-points of the system and their transactions. Sensor data and diagnostic information are pushed from the site to the cloud infrastructure hosted on Amazon Web Services (AWS), which provides storage and analysis services. Commands can be sent to the site to configure sensor-hosts and updates can be patched by developers for the cloud services. [Figure 2](#page-7-2) provides a more detailed view, exposing key sub-systems required for these transactions.



<span id="page-7-2"></span>*Figure 2. System architecture showing key sub-systems and interfaces*



Sensor-hosts are placed within the site to create a self-forming multi-hop mesh network that interfaces with the client/developers with TCP/IP. The sensor-hosts within the WSN are AVR-based microcontrollers (duinoPRO) with digital sensors and Dusty modules which provide communication using Linear Technology's SmartMesh-IP network protocol. Sensor-hosts sample data and diagnostics, and transmit/forward the payload to the centralised network-manager node. The network manager uploads this data using the Node-RED service to AWS.

The payload standard that is sent throughout the network is shown in [Figure 3](#page-8-0)



*Figure 3. Payload structure and evolution from process variables.*

<span id="page-8-0"></span>The sub-systems in AWS integrate with one another to perform two key tasks:

- 1) Parse data sent from the WSN and store it in a structured format for querying, and
- 2) Serve data and controls through a web-application accessible through a HTTP-browser.

The web-application accesses the cloud database, DynamoDB, to process the data for analysis and visualisation. Further, it exposes interfaces that allow users to configure the WSN remotely. The same payload structure is used for this task, with each configuration parameter represented as one field. The web-application is designed with Python Django and orchestrated with Elastic Beanstalk. Orchestration in this context refers to the automaticdeployment and automatic-scaling of infrastructure to serve web-application to clients. This includes virtual servers for hosting the application (EC2), load balancing, and the DynamoDB interface for querying. Additionally, Elastic Beanstalk provides a deployment service that allows developers to rapidly patch the web-application.

Finally, the Amazon API Gateway service provides a means of authentication and interprets and directs in/outbound streams.



### <span id="page-9-0"></span>**3 Summary of Volumes**

A brief summary of the scope and key results for each of the seven individual volumes associated with this report is presented below.

#### **3.1 Volume I: Hardware Design & Communication Protocol**

This volume covers the design of the interposer PCB required to adapt the Dusty module to the duinoPRO. CSC has chosen API UART Mode 2 as the hardware communication protocol due to its energy-efficiency. In addition, CSC has chosen EasyEDA as the PCB vendor to fabricate the PCB as it meets design criteria and is cost effective.

#### **3.2 Volume II: Sensor Driver & Configuration**

This volume covers designs for two classes of subroutines. The first class is for interfacing with the sensor module connected to the duinoPRO microcontroller. This task has been divided between high- and low-level routines for sensor communication. The second class is responsible for configuration of the mote – loading default parameters from non-volatile to program memory and updating these whenever configuration packets are received from the network manager. This volume also includes the project timeline.

#### **3.3 Volume III: System Integration & State Management**

System integration ensures all sub-systems and their interfaces are considered from a holistic standpoint. System integration is managed using design patterns and principles that manages software scope/encapsulation and error handling. This volume further details the state management of the AVR-based microcontroller; the state variables and transitions made during the device's operational lifetime. In particular, sleep management is implemented to ensure optimized battery usage.

#### **3.4 Volume IV: Mesh Network Integration**

Individual motes will interface with the network using Linear Technology's SmartMesh IP network, consisting of a number of mesh systems between motes that relay data to the network manager. When attempting to join the network, each mote will implement a duty cycle management system that prolongs the battery life of the mote in line with the client's requirements. Operational battery life will then be managed by a complex scheduling routine designed to minimise average current while still maintaining reliable sampling at a user configurable rate.

#### **3.5 Volume V: Network Gateway**

This volume discusses the design of the gateway. This device collects and processes all data sent to the network manager from the motes and uploads it to the cloud database. It also sends any data and commands specified by the user to the motes in the local network. CSC has chosen to implement the SmartMesh IP Embedded Manager due to its simplicity to configure and the limited time frame in which to develop this system. The application running on the Gateway will be programmed in Python 2.7 using the Smart Mesh SDK running on a Raspberry Pi 3.

#### **3.6 Volume VI: Cloud Integration**

Upon the successful data extraction from the WSN, the network manager will store its datasets into a NoSQL cloud database. CSC has chosen AWS as the cloud service provider due to its inherent modularity and flexibility in developing basic applications when compared to IBM Watson.

In utilising the AWS resources, CSC has chosen Amazon DynamoDB for its ease of deployment and schema-less characteristics. The implementation of DynamoDB satisfies all the relevant mandatory and aspirational requirements. This volume also includes configuration management.



#### **3.7 Volume VII: Graphical User Interface**

This report pertains to the development and design of the project's web-based graphical user interface (GUI), the link between the end user and the information that is being carried over the network. This includes the selection of the optimal web application framework, the design of the visual interface, and the deployment of the web application. Although the web application's integration with the database will be considered, it excludes design decisions specific to the selection of the database's infrastructure.



### <span id="page-11-0"></span>**4 Requirements**

The extent to which key requirements are expected to be achieved based on the preliminary design is discussed below. The full list of updated design requirements is included in Appendix A – [Updated Requirements Table.](#page-17-2)

Requirement M03 is addressed by the Preliminary Design documentation as a whole.

Volume II details how requirements M07 and M08 will be achieved with regard to obtaining the data readings from the sensors. It also describes how requirement M11 will be addressed. However, it is also noted that M11 may not be fully realised in the first-test prototype due to prioritising meeting and testing most mandatory requirements at the expense of delaying the implementation of M11.

Volume II also details how A03 will be achieved from the perspective of receiving and updating configuration parameters at the sensor motes.

Volume V discusses how requirements A01 and A03 will be satisfied using a flexible packet structure. It also highlights how the configuration of the network manager and gateway will satisfy requirements M06 and A02.



#### <span id="page-12-0"></span>**5 Resources**

Due to the complex nature of the architecture, CSC has leveraged a multitude of resources to assist in the design and implementation of the project. To maintain transparency and quality assurance, the team leveraged GitHub to establish a version control system for all documents used throughout the project [4].

#### **5.1 Hardware**

PCB design will be achieved through EagleCAD, enabling the team to produce a schematic and layout that aligns with electrical protocols and manufacturing standards [5]. EagleCAD was chosen due to the team's previous experience with the software and the portability of the final design. EasyEDA, a web-based electronic design automation tool, was selected for the fabrication of the PCB due to its ease of use and competitive pricing [6].

#### **5.2 Network**

The team has selected a DC2274A-A device to act as the Network Manager. The device was chosen for to its compatibility with the Smartmesh IP that our wireless sensor network implements, as well as the portability associated with a bidirectional USB connection to the gateway [7]. A Raspberry Pi will act as the gateway between the network manager and the database due to its compact size and cost.

#### **5.3 Front End**

CSC has selected AWS as the cloud services platform for the front-office portion of the project. AWS promotes compatibility with many software applications that are able to leverage for cloud-based tasks [8]. Implementation of the database will be achieved using DynamoDB, Amazon's NoSQL database service that handles the routing of data requests, enabling the user to scale the dataset while still maintaining speed and reliability [9]. The team also intends to leverage Node-RED and Node.js to visualise, troubleshoot and optimise the flow of data when needed [10]. Development of the GUI will be achieved by utilising AWS Elastic Beanstalk, enabling simple management of individual applications in the AWS Cloud without having to interface the infrastructure behind each application [11].



### <span id="page-13-0"></span>**6 System Cost**

The WSN comprises of hardware, software and human resource costs [12]. The hardware cost solely consists of the interposer PCB fabrication used to attach the Dusty to the duinoPRO. The software costs are the Asian-pacific marginal provisioned throughput rates used in data transactions. Details information about the PCB vendor or cloudbase service provider and service cost are tabulated in [Table 2.](#page-13-1)



<span id="page-13-1"></span>



# <span id="page-14-0"></span>**7 Top Three Risks**





# <span id="page-15-0"></span>**8 Conclusion**

In recognising the importance of the client's definition of quality, the design decisions have systematically prioritised the mandatory and most desired aspirational requirements respectively.



### <span id="page-16-0"></span>**9 References**

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## <span id="page-17-0"></span>**10 Appendices**

# **Revision History**



### <span id="page-17-2"></span>**10.1 Appendix A – Updated Requirements Table**



<span id="page-17-1"></span>









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